Ownership, Pointer Arithmetic and Memory Separation

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Ownership, Pointer Arithmetic, and Memory Separation

Introduction

Jessie Ownership and Invariants Problems Our Approach

Core Language

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Conclusion

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Context: deductive verification

INRIA Saclay: the Why platform to verify C or Java programs

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Jessie (2/2)



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Jessie

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Ownership and Invariants (1/2)

Examples of invariants:

- ► x ≠ 0
- t.size = length(t.data)
- Tree t is a search tree
- Tree t is balanced

Ownership and Invariants (2/2)

Existing systems:

- ► Spec# / Boogie
- Universes type system
- Capabilities

. . .

And in Jessie?

Problems

Memory model of Jessie:

- Pointer arithmetic
 - Used to encode arrays
 - ► A single pointer may be shifted to access several others
- Memory separation
 - Memory is *split* into several maps from pointers to values
 - Simplifies pointer aliasing problems
 - Global properties of the ownership system are harder to express

Our Approach

- Provide a small core language formalizing ownership and invariants
 - Captures the core ideas of ownership
 - Simple formalization usable in proofs
 - Easy to extend
 - Pointer arithmetic

Express the global properties of the ownership system, in the logic, using assumptions

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Core Language Syntax Semantics Example

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Core Language

Syntax

Values е V Variables х let x = e in eBinding Sequence e: e while e do e **Turing-completion** if e then e else e Test **new** $\langle e; I; \mathbf{r} \rangle$ Allocation !e Dereferencing Assignment e := epack e Packing unpack e Unpacking

Semantics (1/4)

Allocation (p fresh in Γ):

$$\mathsf{\Gamma}; \mathbf{new} \ \langle v; \mathit{I}; \mathbf{r} \rangle \ \ \rightarrow \ \ \mathsf{\Gamma}, \mathit{p} = \langle v; \mathit{I}; \mathbf{r} \rangle^{\circ}; \mathit{p}$$

Assignment:

$$\Gamma, p = \langle v_1; I; \mathbf{r} \rangle^{\circ}; p := v_2 \rightarrow \Gamma, p = \langle v_2; I; \mathbf{r} \rangle^{\circ};$$
 unit

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Semantics (2/4)

Packing (only if I holds in Γ):

$$\Gamma, \left(\begin{array}{c} p = \langle v; I; p_1 \cdots p_n \rangle^{\circ} \\ p_1 = R_1^{\times}, \cdots, p_n = R_n^{\times} \end{array}\right); \text{ pack } p \\ \longrightarrow \\ \Gamma, \left(\begin{array}{c} p = \langle v; I; p_1 \cdots p_n \rangle^{\times} \\ p_1 = R_1^{\otimes}, \cdots, p_n = R_n^{\otimes} \end{array}\right); \text{ unit }$$

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Semantics (3/4)

Unpacking:

$$\Gamma, \begin{pmatrix} p = \langle v; I; p_1 \cdots p_n \rangle^{\times} \\ p_1 = R_1^{\otimes}, \cdots, p_n = R_n^{\otimes} \end{pmatrix}; \text{ unpack } p \\ \rightarrow \\ \Gamma, \begin{pmatrix} p = \langle v; I; p_1 \cdots p_n \rangle^{\circ} \\ p_1 = R_1^{\times}, \cdots, p_n = R_n^{\times} \end{pmatrix}; \text{ unit}$$

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Semantics

Semantics (4/4)

Assignment can only be done on open (unpacked) pointers:

$$\Gamma, p = \langle v_1; I; \mathbf{r}
angle^\circ; p := v_2 \rightarrow \Gamma, p = \langle v_2; I; \mathbf{r}
angle^\circ;$$
 unit

This ensures that invariants are not broken.

Example (1/2)

[Müller, challenges in Java program verification]

Let t be an array of integer of size n.

```
int i, j, count = 0;
for (i=0; i < t.length; i++)
    if (t[i] > 0) count++;
int u[] = new int[count];
for (i=0, j=0; i < n; i++)
    if (t[i] > 0) u[j++] = t[i];
```

This copies the positive elements of t in the new array u.

```
Problem: access u[j++] inside array bounds?
```

Example (2/2)

```
let i = \text{new} \langle 0; \text{true}; \emptyset \rangle in
let i = \text{new} \langle 0; \text{true}; \emptyset \rangle in
let count = new \langle 0; (\lambda p.!p = Card\{i \mid t[i] > 0\}); t[0..n] \rangle in
while !i < n do
  (if |t[!i] > 0 then count := !count + 1;
  i := !i + 1);
pack count;
let u = \text{new} \langle 0; \text{true}; \emptyset \rangle [!count] in
i := 0:
while !i < n do
  (if !t[!i] > 0 then (u[!j] := !t[!i]; j := !j + 1))
  i := !i + 1
```

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Pointer Shifting Extending Allocation Examples

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Pointer Arithmetic

Pointer Shifting

We axiomatize pointer shifting \oplus :

$$p \oplus i = p \iff i = 0$$

 $(p \oplus i) \oplus j = p \oplus (i + j)$

Pointers do *not* have to be all related together by \oplus .

 $p\oplus -1$	p	$p\oplus 1$	$p\oplus 2$	

Extending Allocation

new $\lambda o. \langle v; I(o); \mathbf{r}(o) \rangle [n]$

allocates the following fresh pointers:

$$p \oplus o = \langle v; I(o); \mathbf{r}(o) \rangle$$

where $o \in \{0, \cdots, n-1\}$.

All these pointers are known to be related by \oplus .

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Pointer Arithmetic

Extending Allocation

Examples (1/3)

An array of positive integers:

new
$$\lambda o. \langle 0; (\lambda p.!p \geq 0); \emptyset
angle [n]$$



Examples (2/3)

A pointer on an array of positive integers:

let
$$p = \text{new } \lambda o.\langle 0; \text{true}; \emptyset \rangle [n]$$
 in
new $\langle 0; (\forall o, !(!p \oplus o) \ge 0); p \oplus [0..(n-1)] \rangle$



Examples (3/3)

```
let i = \text{new} \langle 0; \text{true}; \emptyset \rangle in
let i = \text{new} \langle 0; \text{true}; \emptyset \rangle in
let count = new \langle 0; (\lambda p.!p = Card\{i \mid t \oplus i > 0\}); t \oplus [0..n] \rangle in
while !i < n do
  (if !t \oplus !i > 0 then count := !count + 1;
  i := !i + 1);
pack count;
let u = \text{new } \lambda o. \langle 0; \text{true}; \emptyset \rangle [! count] in
i := 0:
while !i < n do
  (if !t \oplus !i > 0 then (u \oplus !j := !t \oplus !i; j := !j + 1))
  i := !i + 1
```

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Memory Separation With One Heap With Multiple Memories Linking Memories Example

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With One Heap (1/3)

Global ownership properties:

- p is closed $\implies Inv(p)$
- p is closed \implies reps of p are owned
- Owner of p is unique

Axioms?

Depends on the heap.

In Spec# / Boogie: *IsHeap*

 $\forall h. \ IsHeap(h) \Longrightarrow Global_ownership_properties(h)$

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With One Heap (2/3)

Another point of view: assumptions

The following code:

x := !y

becomes, at the Boogie or Why level:

assume $Global_ownership_properties(h)$ h := store(h, x, select(h, y))**assume** $Global_ownership_properties(h)$

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With One Heap (3/3)

Suppose a free variable x.

let $y = \text{new} \langle 0; (\lambda p.!p > !x); x \rangle$ in y := !x + 1; pack y; y

Post-condition: |y > |x|

Resulting proof obligation (simplified):

$$\left. \begin{array}{l} \forall h, x, y \\ lsHeap(h) \\ closed(h, y) \end{array} \right\} \Longrightarrow select(h, y) > select(h, x)$$

The heap h is split into several maps from pointers to values.

$$\left. \begin{array}{c} \forall h_{x}, h_{y}, x, y \\ \text{IsHeap}(\ref{eq:hy}, y) \\ \text{closed}(h_{y}, y) \end{array} \right\} \Longrightarrow \text{select}(h_{y}, y) > \text{select}(h_{x}, x)$$

Linking Memories (1/2)

Axiom:

$$\left. \begin{array}{c} \forall h, h_{x}, h_{y}, \\ linked(h, h_{x}) \\ linked(h, h_{y}) \\ lsHeap(h) \end{array} \right\} \Longrightarrow Global_ownership_properties(h, h_{x}, h_{y})$$

Proof obligation:

 $\begin{array}{c} \forall h, h_{x}, h_{y}, x, y \\ linked(h, h_{x}) \\ linked(h, h_{y}) \\ lsHeap(h) \\ closed(h_{y}, y) \end{array} \end{array} \} \Longrightarrow select(h_{y}, y) > select(h_{x}, x)$

This is inconsistent!

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Linking Memories

Linking Memories (2/2)

Solution: use the assumption point of view.

...some code...
assume Global_ownership_properties(Current_heap_x, Current_heap_y)
...some code...

Proof obligation:

 $\left. \begin{array}{l} \forall h_x, h_y, x, y \\ \hline Global_ownership_properties(h_x, h_y) \\ closed(h_y, y) \end{array} \right\} \Rightarrow select(h_y, y) > select(h_x, x) \end{array}$

Example

pack count; while $!i \le n$ do (if $!t \oplus !i > 0$ then $(u \oplus !j := !t \oplus !i; j := !j + 1)$) i := !i + 1

Thanks to memory separation:

Contents of array t is not modified: trivial

Thanks to the invariant system:

All accesses to array u are valid: immediate consequence of closed(count) and the assumed global ownership properties

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Conclusion

The power of the ownership system of Spec#...

- captured in a small core language,
- implemented with pointer arithmetic,
- and memory separation.

Other possible extensions such as classes (implemented in Jessie).

Could be used in ESC/Java, ...